A Unified Approach to Online Matching with Conflict-Aware Constraints

Pan Xu\(^1\), Yexuan Shi\(^2\), Hao Cheng\(^2\), John Dickerson\(^1\), Karthik Abinav Sankararaman\(^1\), Aravind Srinivasan\(^3\), Yongxin Tong\(^2\), Leonidas Tsepenekas\(^1\)

\(^1\)University of Maryland, College Park, USA
\(^2\)BDBC, SKLSD Lab and IRC, Beihang University, China
\(^3\)Department of Computer Science, University of California, Santa Barbara, USA

\{panxu, john, kabinav, srin, llsepene\}@cs.umd.edu, \{skyxuan, haocheng, yxtong\}@buaa.edu.cn

Abstract

Online bipartite matching and allocation models are widely used to analyze and design markets such as Internet advertising, online labor, and crowdsourcing. Traditionally, vertices on one side of the market are fixed and known a priori, while vertices on the other side arrive online and are matched by a central agent to the offline side. The issue of possible conflicts among offline agents emerges in various real scenarios when we need to match each online agent with a set of offline agents. For example, in event-based social networks (e.g., Meetup), offline events conflict for some users since they will be unable to attend mutually-distant events at proximate times; in advertising markets, two competing firms may prefer not to be shown to one user simultaneously; and in online recommendation systems (e.g., Amazon Books), books of the same type “conflict” with each other in some sense due to the diversity requirement for each online buyer.

The conflict nature inherent among certain offline agents raises significant challenges in both modeling and online algorithm design. In this paper, we propose a unifying model, generalizing the conflict models proposed in (She et al., TKDE 2016) and (Chen et al., TKDE 16). Our model can capture not only a broad class of conflict constraints on the offline side (which is even allowed to be sensitive to each online agent), but also allows a general arrival pattern for the online side (which is allowed to change over the online phase). We propose an efficient linear programming (LP) based online algorithm and prove theoretically that it has nearly-optimal online performance. Additionally, we propose two LP-based heuristics and test them against two natural baselines on both real and synthetic datasets. Our LP-based heuristics experimentally dominate the baseline algorithms, aligning with our theoretical predictions and supporting our unified approach.

1 Introduction

Online bipartite matching problems are primarily motivated by the Internet advertising business. In the basic setting, we have a set of offline advertisers and online keywords (impressions). Each time a keyword \( v \) arrives online, a central clearinghouse (such as a search engine or other matchmaking platform) must make an instant and irrevocable decision to either reject \( v \) or assign \( v \) to an advertiser showing interest toward \( v \): the clearinghouse will obtain a profit \( w_{uv} \) as a result. Each advertiser has a unit capacity (can be matched only once) and we aim to design an efficient online algorithm such that the expected total weight (profit) of all matches is maximized. Following the seminal work of Karp, Vazirani, and Vazirani (1990), there has been a large body of research on related variants (see also the survey by Mehta (2013)).

Apart from Internet advertising, online matching and its variants have wide applications in other domains such as crowdsourcing marketplaces (Assadi, Hsu, and Jabbari 2015; Ho and Vaughan 2012) (e.g., Amazon Mechanical Turk, offline tasks vs. online workers), online recommendation systems (Ahmed, Dickerson, and Fuge 2017; Chen et al. 2016b; Sha, Wu, and Niu 2016; Qin and Zhu 2013) (e.g., Amazon Books, offline products vs. online buyers) and ridesharing platforms (Tong et al. 2016a; Dickerson et al. 2018a) (e.g., Uber and Lyft, offline drivers vs. online requests). In many real applications, we need to match each online agent with multiple offline agents simultaneously. A generic model is as follows: we have a set of offline agents \( U \) and online agents \( V \); each online agent \( v \) arrives, we need to immediately and irreversibly decide if we should reject \( v \) or assign \( v \) to a set \( S \subseteq N_u \) (\( N_u \) refers to the set of offline agents interesting to \( v \)). A natural goal is to design an online matching policy such that the total weight among all matches is maximized subject to certain kinds of capacity constraints, e.g., each \( u \) can be matched at most \( c_u \) times while each \( v \) can be matched with a set \( |S| \leq c_v \), where \( c_u \) and \( c_v \) are given as input. In many real applications, there are inherent conflicts among offline agents by nature, which causes significant algorithmic challenges. Consider the following motivating examples.

Event-Participant Arrangement in Social Networks. Li et al. (2014) introduced an interesting event-participant matching problem arising in Event-Based Social Networks (EB-SNs) such as Meetup and Plancast (Liu et al. 2012). In this case, the two sets are offline events and online users. Each time a user arrives, we need to match her to some events she shows interest in. Naturally, there are potential conflicts among a set of events \( S \) with respect to a user if she cannot attend all events in \( S \) on time due to travel/time constraints.

Online Recommendations in E-Commerce. Chen et al. (2016a) studied online recommendations in E-Commerce (e.g., Amazon, Netflix) via online matching models where the two sets are the offline products/items (e.g., books, music, movies) and online users/buyers. Each time an online
Consider the event-participant arrangement. For each user information from as part of input, which can be obtained by integrating all online agents. We assume that for each one.

**Task Assignment in Spatial Crowdsourcing Markets.**

Tong et al. (2016b; 2016a; 2017) considered task assignment problems in spatial crowdsourcing markets where the two sides are the respective set of offline tasks and online workers. In this context, each worker has to travel to the location of a task to complete it and the traveling time dominates the total completion time (e.g., online food delivery services such as Uber Eats). In this case, two offline tasks may conflict for a worker if she cannot complete the two tasks before the respective deadlines.

Conflicting relations among offline agents can be very complicated, causing significant challenges in the modeling. Here are two examples. She et al. (2016) characterized the conflict among events in EBSNs as a collection of conflicting pairs of events. They assume that no user can be assigned to any pair of conflicting events in . Chen et al. (2016a) modeled the conflict in a similar but more soft way: each time an online agent can be assigned a set of offline agents , where the number of conflicting pairs from in should be below a given threshold. Both papers are tightly related and address a common use case—inter-agent conflict—found in many applications; yet, as discussed below, both approaches cannot model the full complexity of many real-world settings.

Both approaches assume that the conflict nature among offline agents applies uniformly to all online agents. This assumption greatly limits the applications. Consider the scenario of event-participant arrangement in EBSNs for example. It is possible that two events conflict for some user but not for due to the different schedules of and different relative distances from and to the two events. The same issue exists in the spatial crowdsourcing markets as well. Another drawback of the state-of-the-art models (She et al. 2016; Chen et al. 2016a) is that they can only capture pairwise conflict relations: what if potential conflicts exist only among at least three offline agents? Consider the scenario of online recommendations and suppose we define a set of offline items as conflicting if it includes more than two items of a single type (thus, we see that no pair of conflicting offline agents exists). Motivated by the wide-ranging applications of those two recent conflict-aware models, in this paper, we propose a unifying model that can help overcome the above two limitations. Next, we briefly discuss our approach (1.1), our contributions (1.2), and additional related work (1.3).

**1 Preliminaries & Brief Overview of our Model**

**Collection of Admissible Sets.** We assume that for each online agent , it has a specific collection of admissible subsets of offline agents. Thus, each time comes online, we need to make an instant and irrevocable decision, either to reject or assign to a subset . We assume , given as part of input, which can be obtained by integrating all information from with that of offline agents. For example, consider the event-participant arrangement. For each user , \( \mathcal{A}_v \) (the collection of feasible sets of events) can be computed after considering her capacity \( c_v \), the distance from to (the set of events interesting to ), schedules of and events in , and the travel options available to . In real applications, \( c_v \) captures the “patience” of the online user toward the offline agents, e.g., the number of recommendations to receive from the system and that of events to attend in EBSNs, which is typically very small. The property of small \( c_v \) values greatly limits the size of \( \mathcal{A}_v \); we will leverage this for model flexibility and algorithmic tractability.

**Known Adversarial Distributions (KAD).** Assume that we have online rounds and a set of online agent types \( V \) (both and are known as input). For each round \( t \in [T] \), an online agent is sampled from \( V \) with probability \( p_{v,t} \) such that \( \sum_{v \in V} p_{v,t} \leq 1 \) for all \( t \). Note that the sampling distributions \( \{p_{v,t}\} \) are independent and allowed to change over time. Current online matching models attacking conflict issues (She et al. 2016; Chen et al. 2016a) both assume adversarial arrival (i.e., the full arrival sequence is completely unknown), which we believe is too conservative. In fact, in many real scenarios, we can predict the arrival patterns of online agents via exploiting historical data (Li et al. 2018; Wang, Fu, and Ye 2018; Yao et al. 2018; Rzeszotarski and Kittur 2011). Note that KAD is a generalization of another well-studied online arrival assumption, Known Identical Independent Distributions (KIID), where the arrival distributions are assumed the same throughout the online phase (Dickerson et al. 2018b; Singer and Mittal 2013; Singla and Krause 2013).

In addition to the above two features, we assume that each offline agent has an integral capacity \( c_v \), the maximum number of times \( u \) can be matched. This is consistent with most current literature. We call our new model Online Matching with Conflict-Aware Constraints under Known Adversarial Distributions (OM-CC-KAD).

**Competitive Ratio.** Let \( \text{ALG}(I,D) \) denote the expected value obtained by an online algorithm \( \text{ALG} \) on an input \( I \) and arrival distribution \( D \). Let \( \text{OPT}(I) \) denote the expected offline optimal, which refers to the optimal solution when we are allowed to make choices after observing the entire sequence of online arrivals. Then, the competitive ratio is defined as \( \min_{I,D} \frac{\text{ALG}(I,D)}{\text{OPT}(I)} \). A common technique is to use a benchmark LP to upper bound \( \text{OPT}(I) \), and hence get a valid lower bound on the target competitive ratio.

**1.2 Our Contributions**

First, we propose a unifying model OM-CC-KAD, which can capture very general conflicting relations among offline agents (which can even be sensitive to each online agent) and also general arrival distributions of online agents (which is allowed to change throughout the online phase).

Second, we show how this model can be cleanly analyzed under a theoretical framework. We first construct a linear program (LP henceforth) LP (1) which we show is a valid
upper-bound on the expected offline optimal (note that the latter is hard to characterize). Next, we propose an efficient LP-based online algorithm that achieves a competitive ratio of at least \(\frac{1}{\Delta + 1} \), where \(\Delta\) is the maximum size of any admissible set. We give a tight online analysis and show further that it has a nearly optimal performance among all possible LP-based online algorithms by presenting relevant hardness results.

**Theorem 1.** LP (1) is a valid benchmark for OM-CC-KAD. There exists an online algorithm based on LP (1), which achieves an online competitive ratio of at least \(\frac{1}{\Delta + 1} (1 - \frac{1}{\Delta + 1}) \geq \frac{1}{e(\Delta + 1)}\). The online competitive ratio analysis is tight.

**Theorem 2.** No online algorithm can achieve a ratio better than \(\frac{1}{\Delta + 1} \) for OM-CC-KAD, if using LP (1) as the benchmark.

To prove Theorem 1, we need to lower bound \(\Pr[\bigwedge_u SF_u]\) for a certain family of negatively correlated events \(\{SF_u\}\) (an upper bound follows directly from the FKG inequality (Fortuin, Kasteleyn, and Ginibre 1971)). For the simple case of unit capacities, we decompose \(\bigwedge_u SF_u\) into an intersection of independent events and hence obtain an exact value for \(\Pr[\bigwedge_u SF_u]\). For the case of general integral capacities, we propose a shadow auxiliary arrival process which is equivalent to the original arrival process but much simpler to analyze. We then try to identify the worst-case scenario on this shadow process where \(\Pr[\bigwedge_u SF_u]\) is minimized. Note that our final ratio result has completely removed the dependency on the maximum weight over all possible online assignments, which appears in the online competitive-ratio results of both She et al. (2016) and Chen et al. (2016a). This is the exact theoretical evidence showing the advantage of shifting from adversarial arrivals to KAD by exploiting historical data—which can be done in many real-world settings.

Third, we propose two LP-based heuristics and test them against two natural baselines, Greedy and Uniform Sampling, on both real (Meetup, (Liu et al. 2012)) and synthetic data. Our experimental results confirm our theoretical predictions about the LP-based heuristics and also show that they can achieve not only significantly better average performances (effectiveness) than the two baselines but also maintain relative low variances (robustness).

### 1.3 Additional Related Work

Online matching models and related variants have been intensively studied during the last decade under different arrival assumptions, including adversarial arrivals, random arrival order and known distributions such as KIID. See the survey (Mehta 2013). The KAD arrival assumption, which is a generalization of KIID, has attracted an increasing number of theoretical and empirical investigations (Alaei, Hajijaghayi, and Liaghat 2012; Alaei, Hajijaghayi, and Liaghat 2013; Dickerson et al. 2018a; Xu et al. 2017).

There are several interesting works which have studied other kinds of constraints imposed on offline agents in different online matching models. Xu et al. (2017) introduced the multiple-budgeted assignment problem arising in crowd-sourcing markets, where each assignment of a task to a worker will consume multiple offline resources. Wang and Wong (2016) introduced the Matroid Online Bipartite Matching model, where the set of all matched offline agents is required to be independent in a given matroid. Kell and Panigrabi (2016) considered Online Budgeted Allocation with General Budgets, where offline agents have multiple tiers of budget constraints forming a laminar structure. There are several interesting matching problems with constraints with applications in the AI and game theory community, which studied the stability and strategic issues, see, e.g., (Kawase and Iwasaki 2018; Goto et al. 2016; Kurata et al. 2017; Aziz et al. 2018).

### 2 Main Model

In this section, we present a formal statement of our main model. Suppose we have a bipartite graph \(G = (U, V)\) where \(U\) and \(V\) represent the offline and online agents respectively. (Since we will not use single edges of \(G\) explicitly, we just refer to \(G\) as \((U, V)\).) We have a finite time (known) horizon \(T\) and for each time \(t \in [T] = \{1, 2, \cdots, T\}\), a vertex \(v\) will arrive (we also say \(v\) arrives or comes) from a known distribution \(\{p_v(t)\}\) such that \(\sum_{v \in V} p_v(t) \leq 1\). Thus, with probability \(1 - \sum_{v \in V} p_v(t)\), no vertex from \(V\) will come. Note that the sampling process is independent across different rounds. For each \(v\), it has an admissible collection of subsets of its neighbors \(\mathcal{A}_v \subseteq 2^U\) such that each \(S \in \mathcal{A}_v\) has cardinality of at most \(\Delta\). Each time a vertex \(v\) arrives, we need to make an immediate and irrevocable decision: either to reject \(v\) or assign \(v\) an admissible set \(S \in \mathcal{A}_v\). Assume that each \(u\) has a capacity \(c_u \in \mathbb{Z}_+\), i.e., \(u\) can be included in at most \(c_u\) different admissible sets. Each assignment \(S\) to \(v\) is associated with a non-negative weight/profit \(w_v(S)\) and our goal is to design an online assignment policy such that the expected total weight of all assignments made is maximized. Note that \(w_v(S)\) can be different for distinct \(v\) even for the same \(S\).

For an assignment \(f = (v, S, t)\) (assignment of \(S \in \mathcal{A}_v\) to \(v\) at \(t\)), let \(x_{v,S,t}\) be the probability that \(f\) is made in any offline optimal algorithm. We use LP (1) as our benchmark LP.

\[
\max \sum_{t \in [T]} \sum_{v \in V} \sum_{S \in \mathcal{A}_v} w_v(S) x_{v,S,t} \tag{1}
\]

\[
\sum_{S \in \mathcal{A}_v} x_{v,S,t} \leq p_v(t) \quad \forall v \in V, t \in [T] \tag{2}
\]

\[
\sum_{t \in [T]} \sum_{v \in V} \sum_{S \in \mathcal{A}_v} x_{v,S,t} \leq c_v \quad \forall v \in U \tag{3}
\]

\[
x_{v,S,t} \leq 1 \quad \forall v \in V, S \in \mathcal{A}_v, t \in [T] \tag{4}
\]

This LP can be intuitively interpreted as follows. Constraint (2) says that for any given \(t\) and \(v\), the probability that we assign \(v\) an admissible set should be no more than the probability that \(v\) arrives at time \(t\). Constraint (3) means that the expected number of times that \(u\) is assigned throughout the \(T\) rounds should be no more than its capacity \(c_u\). The last constraint (4) is due to the fact that all \(\{x_{v,S,t}\}\) are probability values and hence should lie in the interval \([0, 1]\).

The above analysis suggests that any offline optimal solution

\footnote{The collection \(\mathcal{A}_v\) is usually closed under taking subsets, but we do not require it here.}
\{x_{v,S,t}\}$ should be feasible for the above LP. Therefore, we have Lemma 1, which claims that the optimal solution of this LP is an upper bound on the expected offline optimal value.

**Lemma 1.** The optimal value to LP (1) is a valid upper bound for the offline optimal algorithm.

The whole proof mainly consists of justification that any offline optimal strategy \{x_{v,S,t}\} should be feasible for LP (1) and thus the optimal LP value offers a valid upper bound for the offline optimal value. We omit the proof here.

### 3 LP-based Online Sampling Algorithms

In this section, we present a class of parameterized LP-based online algorithms. Suppose \{x_{v,S,t}\} is an optimal solution to LP (1). The main idea behind SAMP (described in Algorithm 1) is as follows. Suppose a vertex \(v\) arrives at time \(t\): we sample an admissible set \(S\) from \(A_v\) with probability \(a x_{v,S,t} / p_{v,t}\), where \(a \in (0, 1]\) is a parameter to be optimized in the analysis. We say a vertex \(u\) is safe (at (the beginning of) time \(t\) iff \(u\) has at least one remaining capacity at \(t\). Consequently, we say an assignment \(f = (v, S, t)\) is safe (or \(S\) is safe at \(t\)) iff each vertex \(u \in S\) is safe at \(t\).

#### Algorithm 1: An LP-Based Sampling Algorithm (SAMP(α))

1. Suppose at time \(t \in [T]\), the vertex \(v\) arrives.
2. Sample an admissible set \(S\) from \(A_v\) with probability \(a x_{v,S,t} / p_{v,t}\).
3. If \(S\) is safe at time \(t\) (i.e., each vertex in \(S\) has at least one capacity), then assign \(S\) to \(v\); otherwise, reject \(v\).

The second step of Algorithm 1 is well defined since we have \(\sum_{S \in A_v} a x_{v,S,t} / p_{v,t} \leq 1\) due to constraint (2) in our benchmark LP.*

**A warm-up analysis for SAMP.** Now we present a warm-up analysis for the case SAMP(1/2) and show that it achieves a ratio at least \(\frac{1}{4}\).

**Theorem 3.** By choosing \(\alpha = \frac{1}{2\Delta}\), SAMP(\(\alpha\)) achieves an online competitive ratio of at least \(\frac{1}{4}\).

The main idea is to prove that each assignment \(f = (v, S, t)\) is successfully made with probability at least \(\frac{x_{f,t}^s}{4\Delta}\). Thus by linearity of expectation and Lemma 1, we get our conclusion.

**Proof.** Without losing of generality (WLOG) assume that \(t = T\) and consider a given assignment \(f^* = (v^*, S^*, T)\). For each \(u \in S^*\), let \(A_u\) be the (random) number of copies of \(u\) exhausted during the previous \(T - 1\) rounds. Suppose \(\mathcal{H}_0 = \{f \neq (v, S, t)| t < T, v \in V, S \in A_v, u \in S\}\), the set of assignments during the first \(T - 1\) rounds where \(u\) is involved. For each assignment \(f = (v, S, t)\), let \(X_f\) indicate if \(f\) is successfully made. Thus we see that \(A_u = \sum_{f \in \mathcal{H}_0} X_f\). Notice

that for each \(f = (v, S, t)\), we have \(E[X_f] \leq \frac{\alpha x_{v,S,t}}{p_{v,t}}\). This is due to the fact that \(f\) is successfully made only if \(v\) comes at \(t\) and \(f\) is sampled. Therefore,

\[
E[A_u] = E \left[ \sum_{f \in \mathcal{H}_0} X_f \right] = \sum_{t \in [T]} v \cdot \sum_{S \in A_v, S \ni u} \sum_{f \in \mathcal{H}_0} X_f \leq \sum_{t \in [T]} v \cdot \sum_{S \ni u} \sum_{f \in \mathcal{H}_0} \frac{\alpha x_{v,S,t}}{p_{v,t}} \leq \alpha c_u \text{ due to constraint (3)}
\]

Thus by Markov’s inequality, \(Pr[A_u > c_u] \leq \alpha\), which implies that \(Pr[A_u \leq c_u - 1] \geq 1 - \alpha\). Let \(SF_f\) be the event that \(f^*\) is safe, i.e., all vertices in \(S^*\) has at least one capacity left at (the beginning of) \(T\). By applying the union bound and our assumption that \(|S^*| \leq \Delta\), we have

\[
Pr[SF_{f^*}] = Pr[\bigwedge_{u \in S^*}(A_u \leq c_u - 1)] \geq 1 - \Delta \alpha
\]

Therefore, \(f^*\) will be successfully made with probability at least \(\frac{\alpha x_{f^*,T}}{p_{f^*,T}} \cdot (1 - \Delta \alpha) = \alpha x_{f^*,(1 - \Delta \alpha)}\). By setting \(\alpha = \frac{1}{2\Delta}\), we get that \(f^*\) is made with probability at least \(\frac{x_{f^*,T}}{4\Delta}\). Thus we get our claim.

**A tight analysis for SAMP.** Consider first the following example which motivates us to obtain the tight analysis.

**Example 1.** Consider the graph \(G = (U, V)\), where \(U = \{u_i | i = 1, 2\}\) and \(V = \{v_j | j = 1, 2, 3\}\). For ease of notation, we directly use \(i\) and \(j\) to denote \(u_i\) and \(v_j\) respectively. Set \(T = 2\) and the arrival distributions are as follows: when \(t = 1\), \(j = 1, 2\) arrives with equal probability \(1/2\) and when \(t = 2\), \(j = 3\) will arrive with probability \(1\). Each \(A_i\) includes only one single set \(S_j\) with \(1 \leq j \leq 3\), where \(S_1 = \{u_1\}\), \(S_2 = \{u_2\}\) and \(S_3 = \{u_1, u_2\}\) with \(\Delta = 2\). Each \(u_i\) has a unit capacity \(c_i = 1\) for \(i = 1, 2, 3\).

Assume all assignments have a unit weight. Let \(f_1 = (v_1, S_1, t = 1)\), \(f_2 = (v_2, S_2, t = 1)\) and \(f_3 = (v_3, S_3, t = 2)\). Consider such an optimal solution to LP(1): \(x_{f_1} = x_{f_2} = x_{f_3} = 1/2\). Let us analyze the assignment \(f_3\) when \(v_3\) comes at \(t = 2\) by running SAMP(\(\alpha\)). Observe that \(f_3\) is safe if both \(u_1\) and \(u_2\) are safe (i.e., both should have one capacity left at \(t = 2\)). According to SAMP(\(\alpha\)), at \(t = 1\) we will choose \(f_1\) with probability \(\frac{\alpha x_{f_1}}{p_{f_1,v_1}} = \alpha\) when \(v_1\) comes at \(t = 1\); similarly we will choose \(f_2\) with probability \(\alpha\) when \(v_2\) comes at \(t = 1\). Notice that at \(t = 2\), \(u_1\) and \(u_2\) each is safe with probability \(1 - \alpha/2\), while both \(u_1\) and \(u_2\) are safe with probability \(1 - \alpha\).

**Remarks.** (1) The key inequality (5) in the proof of Theorem 3 obtained via Markov’s inequality and the union bound is not tight. Consider \(f_3\) in the above example, \(Pr[SF_{f_3}] = 1 - \alpha > 1 - \Delta \alpha\). (2) Unfortunately, the events that different \(u\) are safe are not positively correlated as desired (in which case we can replace the RHS of inequality (5) with the product of probabilities of all \(u\) is safe). Let \(SF_f\) be the event that \(u_i\) is safe at \(t = 2\) in the above example for \(i = 1, 2\). We have shown that \(Pr[SF_1 \land SF_2] = 1 - \alpha < Pr[SF_1] \cdot Pr[SF_2]\).

Next, we prove Theorem 1. Due to space limitations, we present only the proof for the simple case of unit capacities and show that it is the exact case when SAMP achieves
the worst performance. The full proof of the general case is highly technically involved, which we refer to the supplementary materials. The high-level idea for the case of unit capacities is as follows: we try to decompose the event that a given assignment \(f = (v^*, S^*, t^*)\) being safe along the dimension of online time-steps \(t = 1, 2, \cdots, t^* - 1\) instead of each \(u \in S^*\) is safe.

**Proof.** WLOG consider the case \(t = T\) and a given assignment \(f^* = (v^*, S^*, T)\). For each \(t < T\), let \(T_t = \{f = (v, S, t) : v \in V, S \in A_u, |S \cap S^*| \geq 1\}\) be the set of assignments at \(t\) in which the admissible set has at least one element in \(S^*\). Let \(SF_t\) be the event that \(f^*\) is safe at (the beginning of) \(t\). Thus we have \(Pr[SF_T] = 1\) and \(Pr[SF_{t+1} | SF_t] = 1 - \sum_{f \in T_t} ax_f\).

Therefore,

\[
Pr[SF_T] = Pr[\bigwedge_{t<T} SF_t] = \prod_{t=1}^{T-1} Pr[SF_{t+1} | SF_t] \\
= \prod_{t=1}^{T-1} \left(1 - \sum_{f \in T_t} ax_f\right) \quad \text{(6)}
\]

Here are two useful observations. First, for each \(t < T\),

\[
\sum_{f \in T_t} ax_f \leq \sum_v \sum_{S \in A_u, \Delta_v \geq \Delta} ax_{v,S,T} \\
\leq \sum_v \alpha p_{v,t} \leq \alpha \quad \text{(due to constraint (2))}
\]

Second,

\[
\sum_{t<T, f \in T_t} ax_f \leq \sum_{u \in S^*} \left(\sum_{t<T, v \in V, S \in A_u, S \supset u} ax_{v,S,t}\right) \\
\leq \sum_{u \in S^*} \alpha \Delta \quad \text{(due to constraint (3))}
\]

The first observation says that each term after the minus symbol in the product (7) is at most \(\alpha\) while the second indicates the sum of all those terms (after the minus) over \(t\) is at most \(\alpha\). Therefore, we claim that the product (7) has a minimum value of \((1-\alpha)^3\). This implies that \(f^*\) will be successfully made with probability at least \(\alpha x_{f^*} (1-\alpha)^3\). By choosing \(\alpha = 1/(\Delta + 1)\) and using linearity of expectation, we prove our claim.

The example below shows that the above analysis is tight.

**Example 2 (Tight Example).** Consider the graph \(G = (U, V)\) where \(U = \{u_i | i \in [m]\}\), \(V = \{v_j | j \in [n]\}\) with \(m = \Delta, n = T = \Delta + 1\). For ease of notation, let us use \(i\) and \(v_j\) to denote \(u_i\) and \(v_j\) respectively for \(i \in [m], j \in [n]\). For each \(t \in [T]\), \(p_{j,t} = 1\) iff \(j = t\) and 0 otherwise (hence at time \(t\), vertex \(j = t\) arrives surely). For each vertex \(v_j\), its corresponding admissible collect \(A_{v_j}\) includes only one single subset \(S_j\), where \(S_j = (u_i, i = j\) for each \(j \in [n-1]\) and \(S_n = U\) and thus the largest size of \(|S_j| j \in [n]\) is equal to \(\Delta\). Set \(c_1 = 1\) for all \(i \in [m]\) (all \(u_i\) have a unit capacity).

For each \(j \in [n]\), let \(f_j = (v_j, S_j, t = j)\) be the only possible assignment associated with \(v_j\) when it comes at \(t = j\). Set \(x_j = x_{f_j}\) and consider such an optimal solution to LP (1):

\[
x_j^* = 1 - \epsilon \quad \text{for each} \quad j \leq \Delta \quad \text{and} \quad x_{f_j}^* = \epsilon \quad \text{(we can always make such a feasible solution to be optimal by choosing a proper weight vector)}
\]

Now consider the assignment \(f_n = (v_n, S_n, t = T)\) when the last vertex \(v_n\) comes at \(t = T\). Let us compute the probability \(Pr[SF_{f_n}]\) that \(f_n\) is safe in SAMP(\(\alpha\)). Observe that assignment \(f_n\) will be safe iff none of \(f_j, j < n\) is successfully made before.

Notice that at each time \(t < T\), SAMP(\(\alpha\)) will successfully make the assignment \(f_j = (v_j, S_j, t = j)\) with probability \(\frac{ax_j}{p_j} = \alpha (1-\epsilon)\).

This implies that \(Pr[SF_{f_n}] = (1-\alpha (1-\epsilon))^3\), which essentially matches the lower bound we compute for \(Pr[SF_{f_n}]\) in the proof of Theorem 1.

### 4 Hardness Results

In this section, we prove Theorem 2. The big idea is to reduce the classical \(k\)-uniform hypergraph matching to a special case of OM-CC-KAD with \(\Delta = k\).

**Proof of Theorem 2.** Consider a given \(k\)-uniform hypergraph \(H = (U, E)\), where \(U\) and \(E\) are the respective set of vertices and hyperedges with \(|U| = m\) and \(|E| = n\). Thus we have that each hyperedge has a cardinality of \(k\). A hypermatching on \(H\) is a set of hyperedges which is mutually disjoint. Based on \(H\), we create an instance \(I(H)\) of OM-CC-KAD as follows. Set the offline and online sets of vertices as \(U\) and \(E\) respectively. Let \(E = \{f_j | j \in [n]\}\) and we view each hyperedge as an online vertex in our case. Let \(T = n\) and for each \(t \in [T]\), \(p_{j,t} = 1\) iff \(j = t\) and 0 otherwise. In other words, at time \(t\), \(f_{j,t}\) comes surely and no other vertex will come. For each \(f_j\), it has a single admissible set \(S_j = f_j \subseteq U\) (recall that \(f_j\) is a hyperedge, i.e., a subset of \(U\)). Thus in our case \(\Delta = \max_j |S_j| = k\). Assume all admissible sets have a unit weight and set \(c_u = 1\) for all \(u \in U\).

Let \(LP(H)\) be the standard relaxed LP for \(H\) (we use \(LP(H)\) to denote the optimal LP value as well). Similarly, assume \(LP(I(H))\) as the benchmark LP (1) for \(I(H)\). We can verify that \(LP(H)\) is essentially the same as \(LP(I(H))\) and thus the optimal values are the same. Note that any feasible set of assignments \(\{f_j\}\) collected by any online algorithm surely form a hypermatching over \(H\). Thus, we claim that \(OPT(I(H)) \leq OPT(H)\), where the former is the optimal online performance while the latter is the maximum size of matching over \(H\). From (Füredi, Kahn, and Seymour 1993) we see that there does exist some \(\mathcal{H}^*\) such that \(OPT(I(H^*)) \leq \frac{1}{k-1+1/k}\). Thus we claim that \(OPT(I(H^*)) \leq \frac{OPT(H)}{LP(I(H^*))} \leq \frac{1}{k-1+1/k}\). 

### 5 Experiments

In this section, we present our experimental results. We test SAMP against several natural heuristic baselines on both the Meetup dataset (Liu et al. 2012) and synthetic datasets. The details of our datasets and experimental setup are as follows.

**Meetup dataset and experimental setup.** We use the Meetup dataset from (Liu et al. 2012) collected between Oct. 2011 to Jan. 2012. Meetup\(^3\) is a social platform which facilitates pairing users with their target events. In this dataset, there are three entities: users, events and groups. Every user and event is associated with a geographic coordinate. Users and groups are associated with tags which show the corresponding features. Every event inherits the tags of the group hosting the event. In our experiment, we focus on the city of San Francisco, and extract users and events with longitude and latitude in ranges (-122.3475, -122.5201) and

\(^3\)https://www.meetup.com/
(37.7112, 37.8153) respectively. Table 1 presents the statistics of the extracted data. The number of events attended by users and that of users admitted by events both follow Pareto distributions (visualized in the supplementary materials).

<table>
<thead>
<tr>
<th>Statistic</th>
<th># users</th>
<th># events</th>
<th>Avg. # events per user</th>
<th>Median # events per user</th>
<th>Avg. # users per event</th>
<th>Median # users per event</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>13492</td>
<td>13596</td>
<td>6.02</td>
<td>2</td>
<td>5.97</td>
<td>3</td>
</tr>
</tbody>
</table>


In our experimental setup, we randomly sample 50 events (U) and 100 users (V) from the extracted data. We compute the weight/profit of each assignment similar to (She et al. 2016). First, we manually cluster tags with similar meanings and select the 20 most popular tags. Then, we represent each user u and event v as a canonical binary vector of dimension 20 over the selected tags (denote by \( I_u \) and \( I_v \) respectively). For each pair of event u and user v, we define the similarity between \( u \) and \( v \) as \( w(u,v) = 1 - \frac{|I_u \cdot I_v|}{|I_u| \cdot |I_v|} \), where \( |I_u \cdot I_v| \) denotes the Euclidean distance and the denominator \( \sqrt{20} \) is to ensure that \( w(u,v) \in [0,1] \). For each subset \( S \subseteq U \), we define \( w_v(S) = \sum_{u \in S} w(u,v) \). For each event u and user v, let \( c_{uv} \) and \( \tilde{c}_v \) be the respective number of users that u admitted and number of events that v attended. We set capacity \( c_v = \tilde{c}_v \) and choose \( c_v \in \{ \frac{1}{3} \tilde{c}_v, \frac{2}{3} \tilde{c}_v, \tilde{c}_v \} \) (since the dataset is collected over 3 months we offset user’s capacity accordingly). The dataset does not include, explicitly, the conflict information over events and we generate the collection of admissible sets \( \mathcal{A}_v \) for each user v as follows. We set \( N_v = 2c_v \) and \( A_v = 2N_v \). Select \( N_v \) nearest events to v from U as the neighbors of v (denoted by \( N_v \)). We sample \( c_v \) events from \( N_v \) uniformly with replacement and set an admissible set S as the set of all distinct events sampled. We repeat this process until we get \( \min(A_v, 2N_v - 1) \) different admissible sets. Set \( T = 1000 \) and for each time t \( \in T \), we generate a random vector \( \{p_{v,t}\} \) such that each \( p_{v,t} \) takes a uniform value from [0,1] and \( \sum_v p_{v,t} = 1 \).

**Synthetic datasets.** We set \(|U| = 50\) and \(|V| = 100\), i.e., 50 events and 100 user types. For each user v, we generate its neighbor \( N_v \) by independently sampling each u with probability \( p \), where \( p \) is a given parameter. Let \( N_v = |N_v| \); we set \( c_v = \max(S, \frac{N_v}{2}) \) and \( A_v = 2N_v \). After obtaining \( N_v, c_v \) and \( A_v \), we generate the collection of admissible sets \( \mathcal{A}_v \) for each user v similar to that in the real dataset. Thus each \( S \in \mathcal{A}_v \) has size at most \( c_v \) and \( \mathcal{A}_v \) has at most \( A_v \) sets. Let \( C_U \) be an upper bound of the capacity for all events and for each event v, we sample a value from \( C_U \) according to the distribution learned from the extracted dataset (with appropriate scaling such that the total sum is 1). For each pair \( (u,v) \), we sample a uniform value \( w(u,v) \) in [0,1] and set \( w_v(S) = \sum_{u \in S} w(u,v) \) for each \( S \in \mathcal{A}_v \). The generation of arrival distributions of \( \{p_{v,t}\} \) is the same as that in the real dataset. In our experimental setup, we have three parameters \( (C_U, T, p) \), where \( T \) is the number of online rounds. We generate a set of instances by varying one single parameter over a range and fixing all other parameter on the default value. Table 2 summarizes the details.

<table>
<thead>
<tr>
<th>Factors</th>
<th>Setting</th>
</tr>
</thead>
<tbody>
<tr>
<td>( C_U )</td>
<td>6, 8, 10, 12, 14, 16, 18, 20</td>
</tr>
<tr>
<td>( T )</td>
<td>100, 200, 300, 400, 500, 600, 700, 800, 900, 1000</td>
</tr>
<tr>
<td>( p )</td>
<td>0.05, 0.1, 0.15, 0.2, 0.25</td>
</tr>
</tbody>
</table>

Table 2: Synthetic dataset, the default settings are marked as bold.

**LP-based heuristics and baselines.** We propose two LP-based heuristics—SAMP(1) and SAMP(0.8)—and test these two against two other baselines, namely Greedy and Uniform Sampling. The details of these algorithms are as follows. Consider a user v arriving at time t.

- **SAMP(1):** Samples an admissible set \( S \in \mathcal{A}_v \) with probability \( x_{v,S,t}/p_{v,t} \) and assigns S to v if S is safe.
- **SAMP(0.8):** Samples an admissible set \( S \in \mathcal{A}_v \) with probability \( 0.8x_{v,S,t}/p_{v,t} \) and assigns S to v if S is safe.
- **Greedy:** Assigns v a safe admissible \( S \in \mathcal{A}_v \) which has the maximum weight \( w_v(S) \) among all safe choices at time t (breaking ties arbitrarily).
- **Uniform:** Samples a set \( S \in \mathcal{A}_v \) uniformly and assigns S to v if S is safe.

Note that among the above four algorithms, only Greedy is adaptive in the sense that its strategy responds to the outcome of previous strategies. We test the algorithm SAMP(α) as suggested by Theorem 1 with \( \alpha = \frac{1}{\Delta} \) where \( \Delta = \max(c_v) \) is the largest possible size over all possible admissible sets. On practical instances, we find SAMP(\( \frac{1}{\Delta} \)) is too conservative and works optimally only for the theoretical worst case as shown in Example 2. As shown in Figures 1 and 2, heuristics of SAMP(α), with larger α values, (e.g., 1 and 0.8 here) work much better in both real and synthetic datasets.

**Methodology.** We solve all LPs via the Glop Linear Solver\(^*\) on commodity hardware: an Intel Core i7-7700 (2.80 GHz) machine with 16GB of main memory. For most of the instances on both real and synthetic datasets, the LPs can be solved within 30 seconds. For each generated instance (synthetic and real), we run each of the four algorithms for 1000 independent trials. For the real case, we output the maximum, third quartile, median, first quartile, minimum (the four lines from top to down) and average (the cross) among the 1000 trials in a box plot. For the synthetic case, we simply take the average as the final performance. We compute the ratio of the performance of each algorithm to the optimal value of the corresponding LP as the final competitive ratio. The results of the four algorithms on the different settings of the real and synthetic datasets are summarized respectively in Figures 1 and 2.

**Discussion.** Overall, our LP-based heuristics work much better than the two baselines. We observe that SAMP(1) > SAMP(0.8) > Greedy > Uniform overall. Notably, SAMP(1) can beat the rest two baselines by a non-trivial

\(^*\)https://developers.google.com/optimization/lp/glop
Figure 1: Competitive ratios achieved by our two LP-based methods, SAMP(1) and SAMP(0.8), and the two baseline methods, Greedy and Uniform, on the real-world Meetup dataset (Liu et al. 2012).

Figure 2: Competitive ratios achieved by our two LP-based methods, SAMP(1) and SAMP(0.8), as well as two baseline methods, Greedy and Uniform, on a synthetic dataset.

The experimental setup, $\Delta = \max_v c_v$, also gets larger, thus SAMP expects worse performance by Theorem 1.

6 Conclusion

In this paper, we proposed a unifying model of online matching with offline conflict-aware constraints, a setting that arises in many practical applications where interactions or constraints exist between agents or items on the same side of the market. Our model can capture very general conflict constraints over the offline agents; it also allows the arrival distributions of online agents to change over the online phase. We proposed an LP-based online algorithm with provable performance.

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